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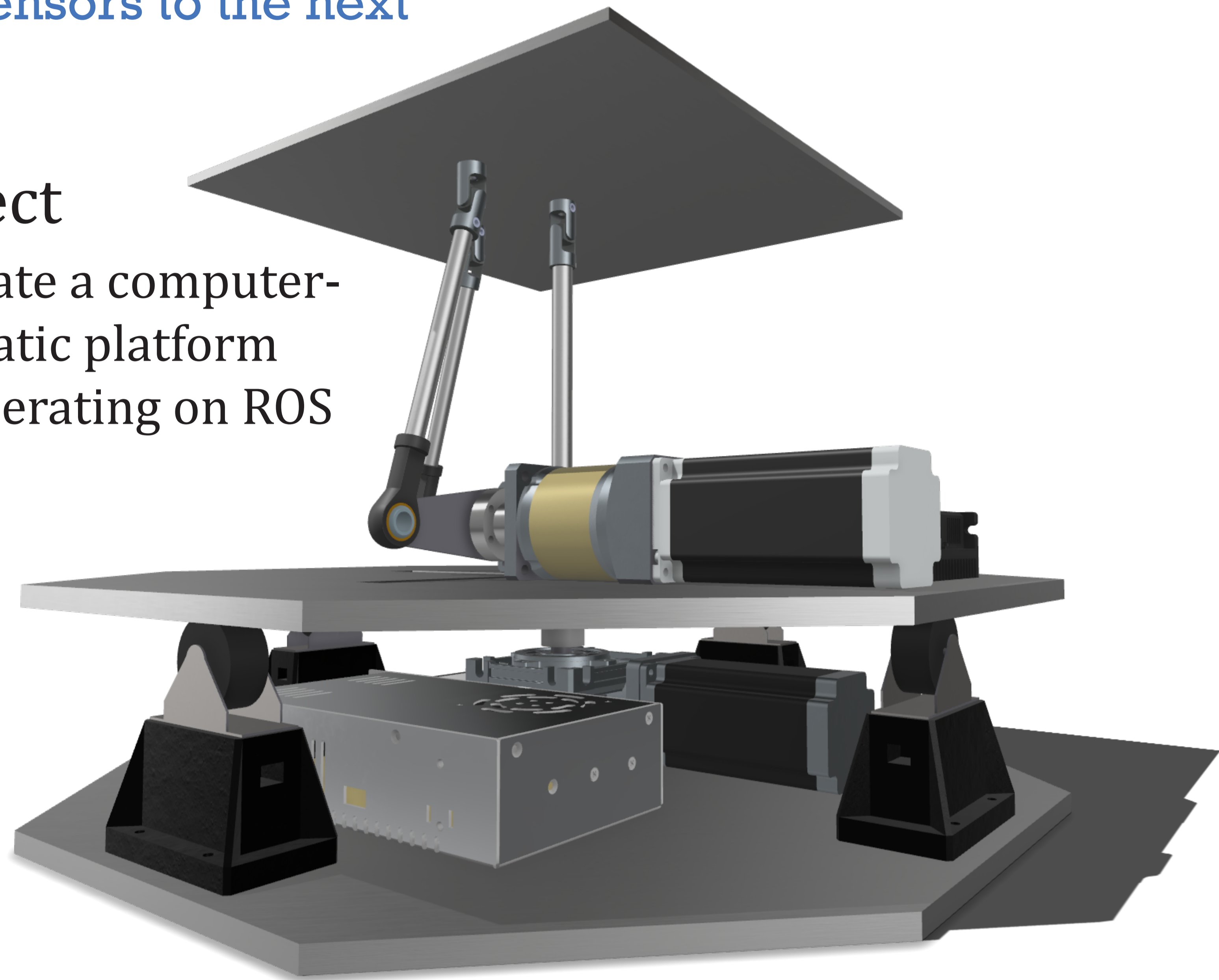


# Sensor calibration platform

Calibrate your sensors to the next level

## The goal of the project

The objective was to create a computer-controlled 3-DOF kinematic platform for sensor calibration operating on ROS interface



## Performance

- $\pm 45$  degrees rotation per axis
- Up to 20 kg payload
- Low jitter

