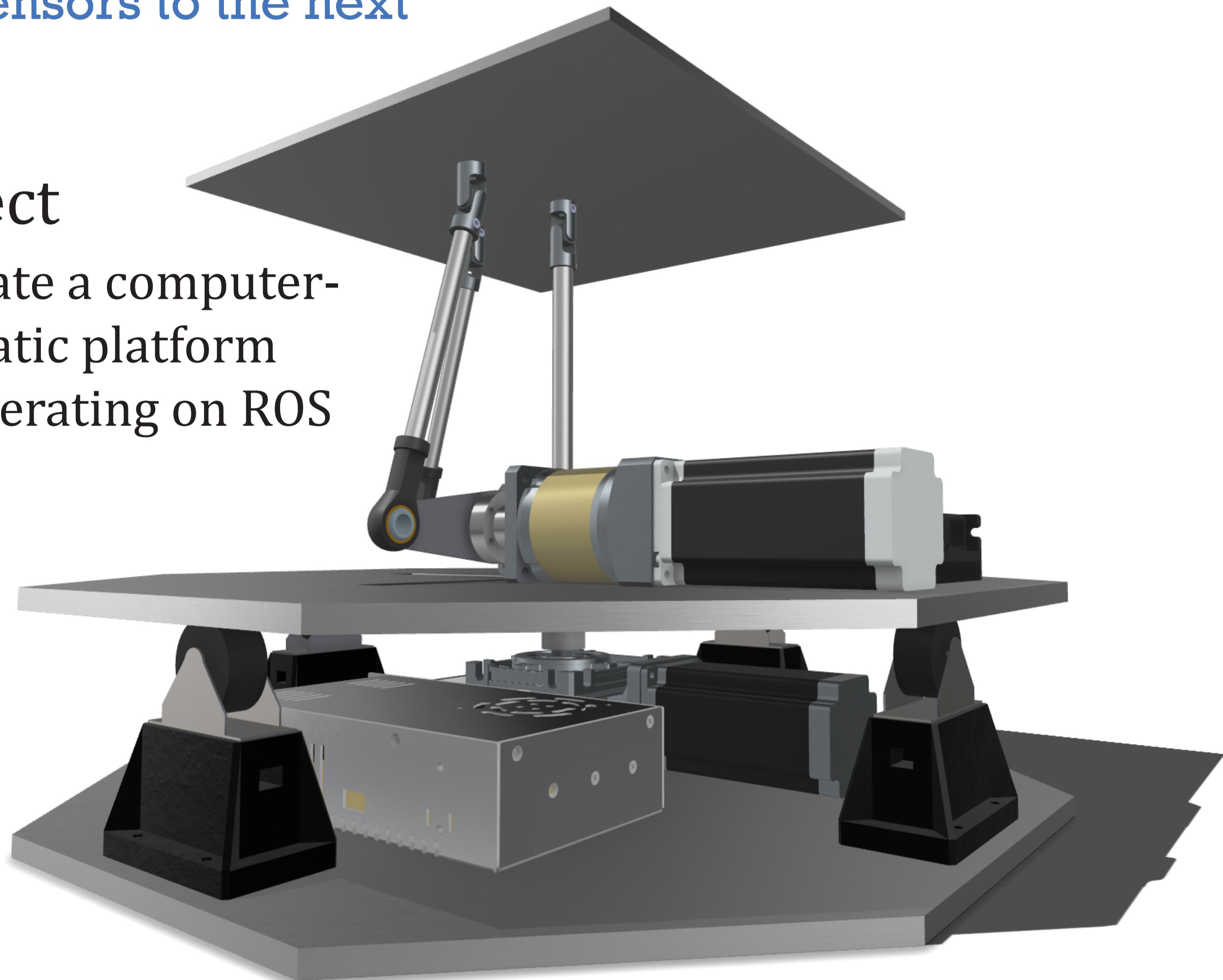


# Sensor calibration platform

Calibrate your sensors to the next  
level

## The goal of the project

The objective was to create a computer-controlled 3-DOF kinematic platform for sensor calibration operating on ROS interface



## Performance

- $\pm 45$  degrees rotation per axis
- Up to 20 kg payload
- Low jitter

